

Environmental and Social Planning for Offshore Hydrocarbon E&P Projects

AGENDA – Offshore Drilling

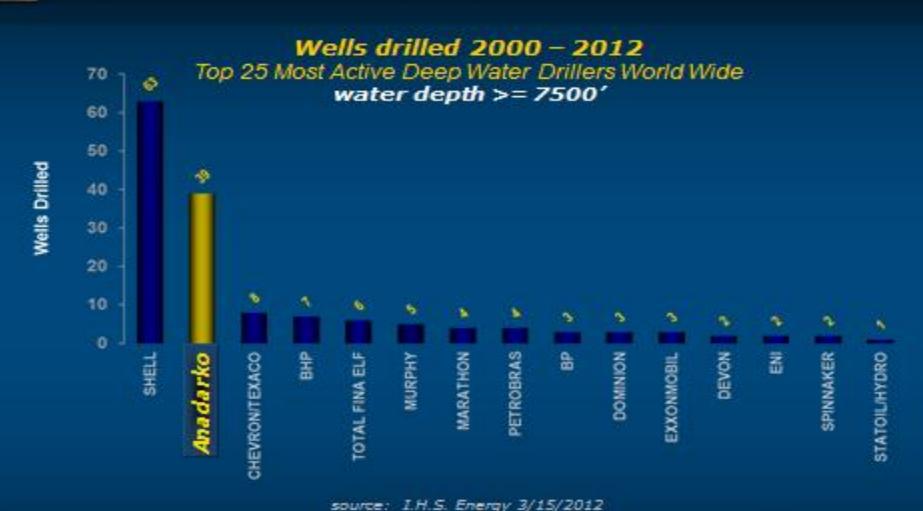
- 1) Introduction Anadarko International Deepwater Drilling
- 2) Types of MODUs and Specialized Equipment
- 3) Planning and Preparation
- 4) Mobilization
- 5) Execution
- 6) Demobilization
- 7) Treatment and disposal of Drilling Fluids

Introduction - Anadarko International Deepwater Drilling



Introduction - Anadarko International Deepwater Drilling

Deep Water Drilling Experience



TYPES OF Mobile Offshore Drilling Units (MODU)

Bottom Supported MODU

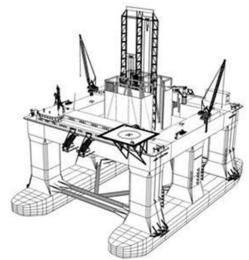
- Jack-up
- Submersible
- Maximum water depth ±190m for Ultra-Premium Jackups

Floating MODU

- Semi-submersible
- Drill ship
- Either can be moored (anchored) or dynamically positioned (DP)
- Water depths to 4,000m

Key Elements

- Self-contained for extended periods
- Includes drilling package, cranes, material storage, crew accommodations, heliport, power generation
- Requires Vessel Support to Supply



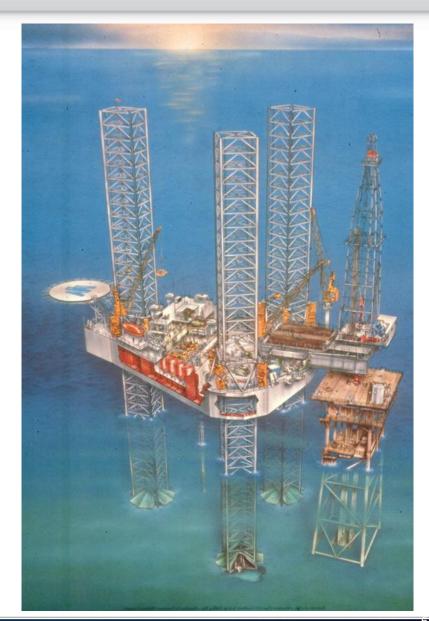




TYPES OF MODU's - JACKUP

Bottom Supported MODU - Jackup

- Towed to location with barge afloat
- Movable legs lowered to seafloor
- Pre-load required prior to "jacking up" into position
 - Reduce the risk of "punch through"
- Barge is raised out of water by jacking against the legs
- Provides very stable platform
 - No Movement in Work Platform
- Drilling depths to 12,000m
- Maximum water depth ±150m



TYPES OF MODU's – Floating Rigs

- Typically, in water depths >150m, bottom supported rigs become impractical, and the industry uses floating rigs in water depths exceeding 150m
- Floating MODU types
 - Semi-submersible barge
 - Drill ship
- Floating rigs can be moored (anchored) subject to limitations of anchor chain-cable and winch systems or dynamically positioned (DP)
- Additional equipment is required to accommodate vessel movement (heave, pitch and roll)
 - Motion compensation system
 - Subsea blowout preventers (BOP) & Controls
 - Marine riser system
 - Remotely operated vehicle (ROV)



TYPES OF MODU's - Moored vs. DP

■ Moored – is practical to water depth limits of ±1,500m

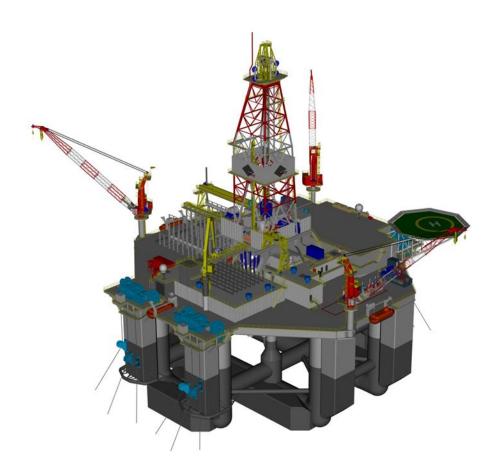
- Material storage is limited by buoyancy & deck space, ± 4,000 MT
- Weight & storage volume of mooring wire & chain require large/ heavy duty winching systems

■ DP – is practical to water depth limits of ±3,658m

- Ship shape designs have much more deck/hold area than semisubmersibles
- Load capacity often exceeds 20,000 MT for late generation drill ships
- Limiting factor is ability to hold top tension on the marine riser
- Seafloor transponders & GPS are used to establish well location and maintain position
- Multiple DP thrusters operate 24hr/day to maintain the ships position over the well
- The MODU's stability is maintained by the transfer of sea water into dedicated ballast storage compartments.

TYPES OF MODU's - Moored Semi-submersible

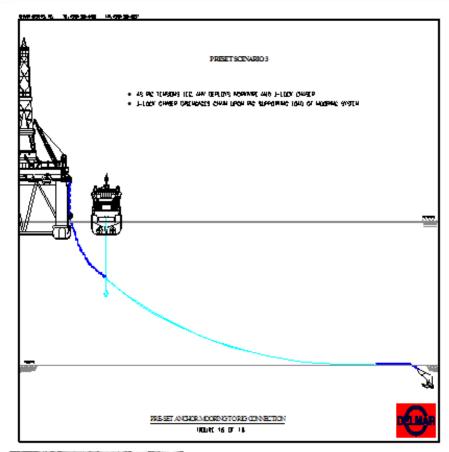
- Towed to drill site at shallow draft
- At drill site, the mooring system is deployed (utilizing AHV), and the MODU is held in place w/ anchor & chain
- After mooring, the hull is ballasted down to provide stability and lower the COG.
- This design offers better motion characteristics than early drill ship designs
 - Smaller water plane profile & lower center of gravity minimizes vessel motion



TYPES OF MODU's - Mooring Operations

- Anchor mooring & recovery may require up to 6-8 days
- Anchor setting is further complicated by too soft, too hard, or uneven seafloor conditions
- Requires very specialized, high HP vessels, winches & crews to safely place anchors in the desired pattern







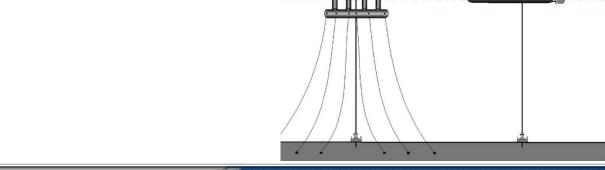


TYPES OF MODU's - Dynamically Positioned Drill Ship

- Vessel sails to site under its own power
- Vessel remains on station using 'dynamic positioning' (DP)
- DP set up is much faster, since mooring is not required (6-18hr vs 6 days) and transponder retrieval is also faster
- Multiple DP thrusters operate 24hr/day to maintain the ships position over the well
 - The MODU's stability is maintained by the transfer of sea water into dedicated ballast storage compartments.

Higher fuel usage due to significant power required to operate

thrusters 24hr/day





TYPES OF MODU's - Dynamic Positioning



- Initial position established by global positioning system (GPS)
- Seabed transponders (4 to 6) deployed in predetermined pattern w/ ROV
- Absolute position is continuously received from the vessel's GPS system
- Vessel's acoustic transceiver regularly queries the seabed transponders to determine relative position
- Computer processes inputs and adjusts power
 & azimuth of thrusters to hold the rigs position

Bolette Dolphin

Construction: HHI at Ulsan S. Korea

Design: MSC P10000 Drillship

Dimensions: 752' x 118'/229 m x 36 m

Dual Derrick: (NOV)

• Water Depth: 12,000'/3658 m

Drilling Depth: 40,000'/ 12,192 m

Variable Deck Load: 20,000 m-tonnes

Quarters: 210 beds

• Thrusters: 6 x 5500 kw x 1.35 (44,500 hp)

Power Generation: 6 x 8000 kw x 1.35 (64,800 hp)

2 BOP / LMRP Stacks



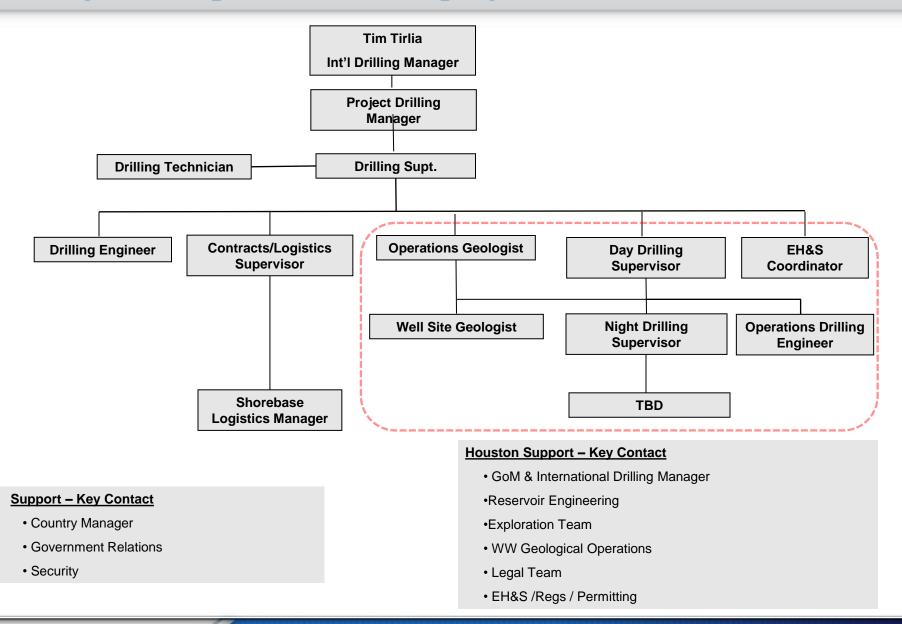
Remotely Operated Vehicle (ROV)

- Provide subsea monitoring & intervention capability
 - High resolution video
 - Manipulation of simple tools &/or BOP controls
- Perform seafloor surveys
- Placement of seabed transponders
- Visual operation of riserless operations
- Inspection of wellhead, riser and BOP





Planning and Preparation: Developing a Team



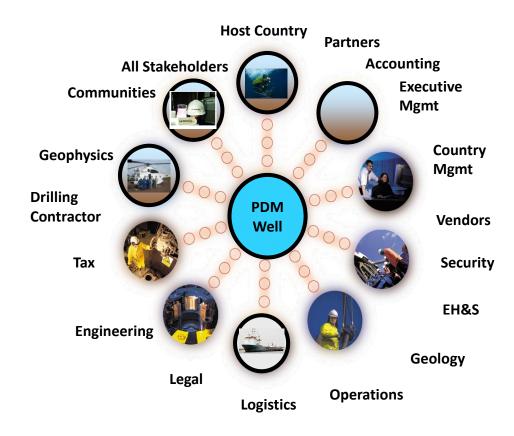
Planning and Preparation: Plan for the Unknowns

International Drilling Campaigns – Deep Water

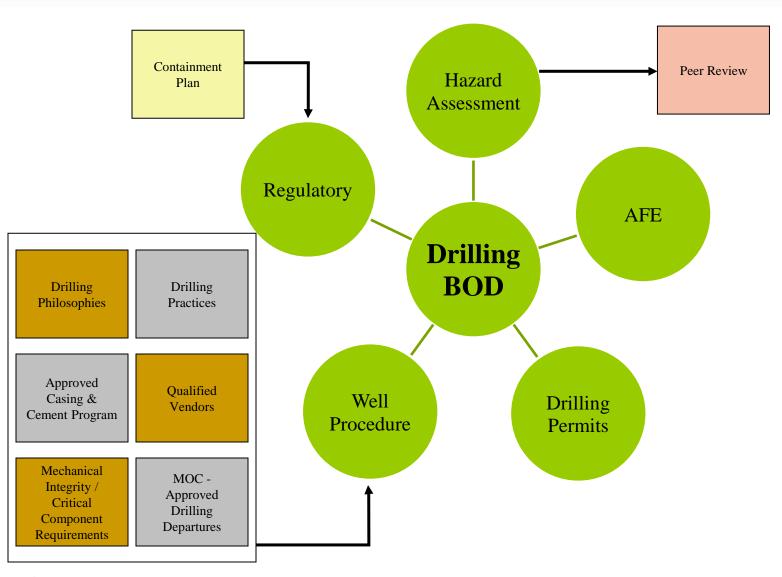
- Early Commitment to Drilling Schedule
- Work Scope / Cost Creep
- Rig & Equipment Importation/Exportation
- Managing FCPA
- Staffing from Exploration to Development
- Managing Expectations
- Managing the Unknowns
- Performance on first attempt
- Security Protection
 - Law Enforcement/Military Relations
 - Establish Rules of Engagement
 - Piracy Plan



Planning and Preparation



Planning and Preparation: Develop the well Basis of Design (BOD)



Planning and Preparation: Capping Stack

APC is a member of Wild Well **Control**

> with access to:

- Debris Removal Equipment
- Subsea Dispersal Materials & Equipment
- Capping Stack
- Technical Expertise (Planning & Execution)



Planning and Preparation: Complexities of Deepwater Drilling

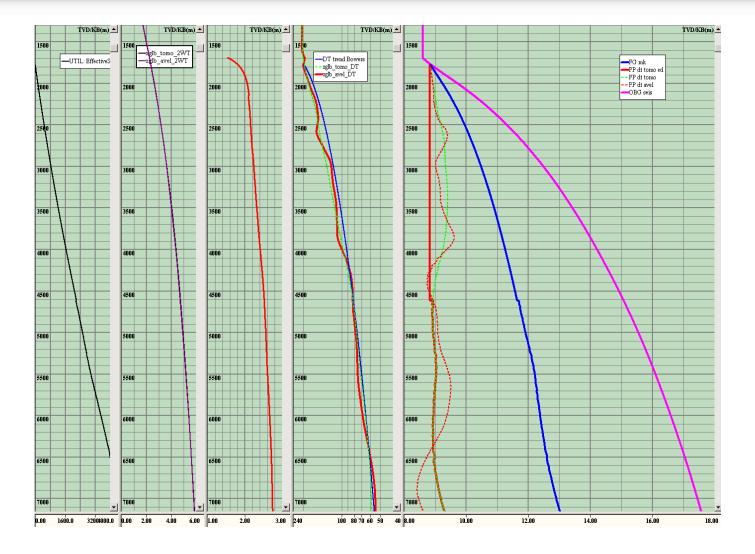
Drilling

- Tight Margin Between Fracture Gradient & Pore Pressure
- Hydrate Formation during Well Control
 - Gas & Water at pressures Form Ice
 - Typically Use LTSBM (Non-water Based)
- Kick Detection
 - Avoid Riser Evacuation
 - Significant portion of circulating volume above BOPs
 - 15 bbl/9.2 ppg kick @ 3300 mtrs=34 bbls @ 1468 mtrs or 5300 bbls @ surface
- Variability of Temperature
 - Surface Ambient
 - *Mudline* 36-42°F
 - Bottom Hole Temperature >150°F
- Operational Cost
 - ±1MM US\$/day

Rig Related

- Environmental, Health & Safety
 - +/-160 Personnel onboard
 - Maintaining Acceptable Culture
- Station Keeping
- Coordination between Departments
 - Marine
 - Mechanical
 - Drilling
- Complexity of Systems
 - BOP Control System
 - Marine Systems
- Maintenance of Systems
 - Offline Maintenance
 - Preventative Maintenance
 - Rig Repairs

Planning and Preparation: Pore Pressure/Frac Gradient Curve



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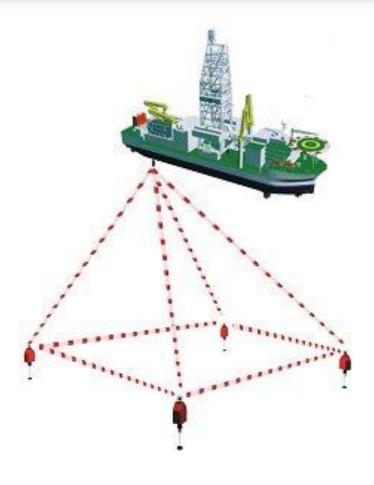
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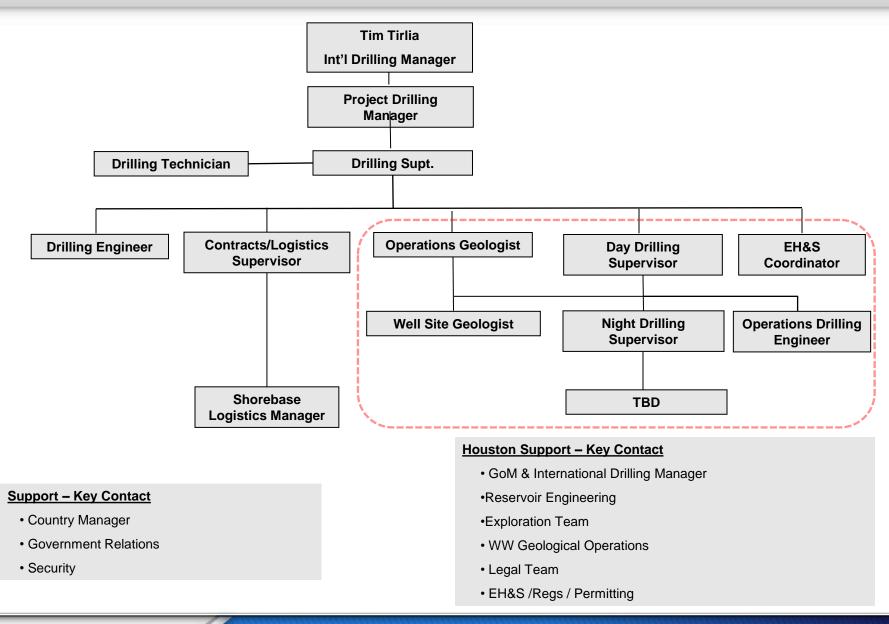
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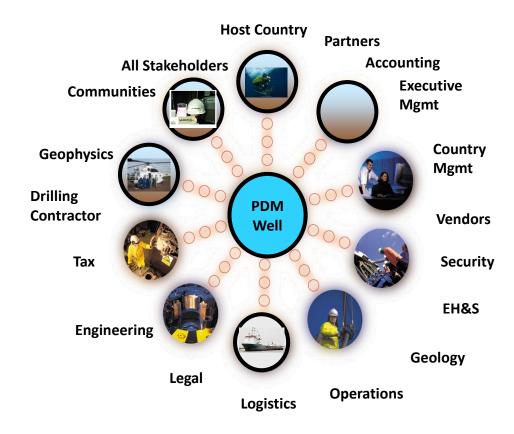
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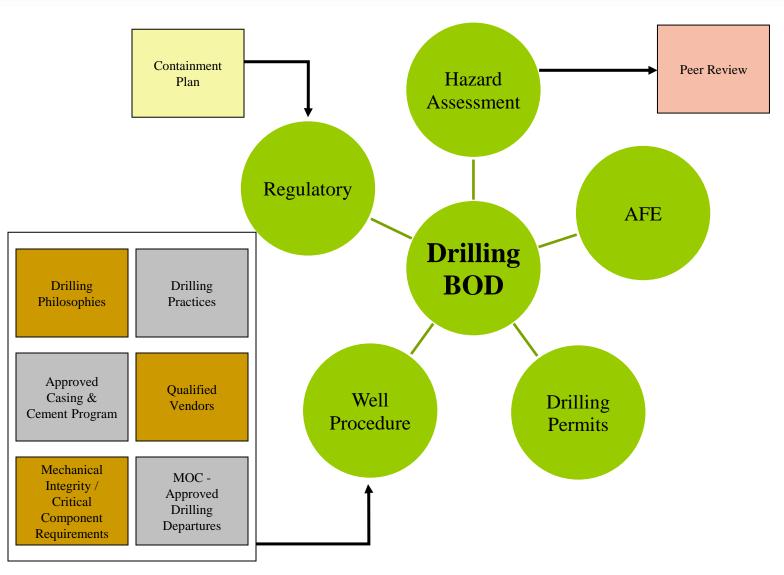
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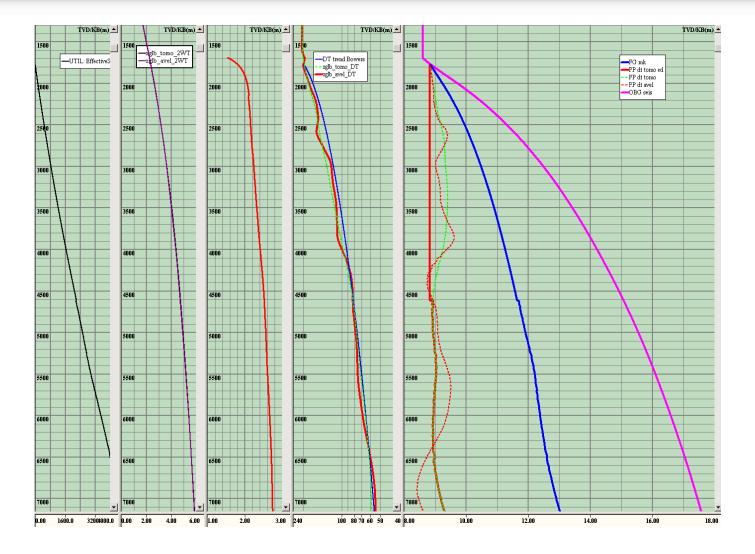
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Rig Related

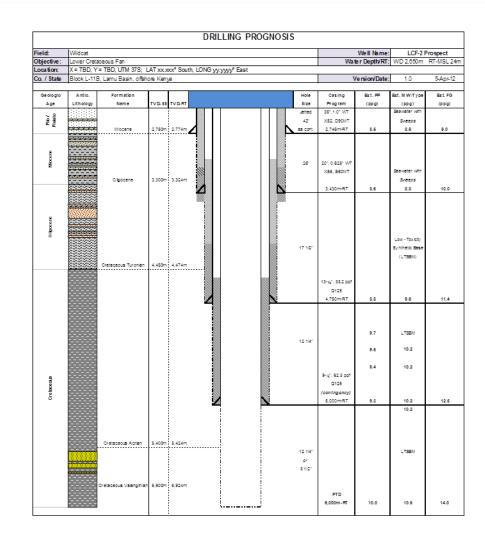
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Planning and Preparation: Pore Pressure/Frac Gradient Curve



Planning and Preparation: Pre-Drill Planning

- Four casing strings typical
 - Isolation of perceived / potential pressure regimes
 - Well control requirements
 - Hole sizes compatible with evaluation program
 - Common international program
- Low toxicity, synthetic base mud (LTSBM) selected to avoid formation of gas hydrates during possible well control events



Planning & Preparation: Typical Formation Evaluation Objectives

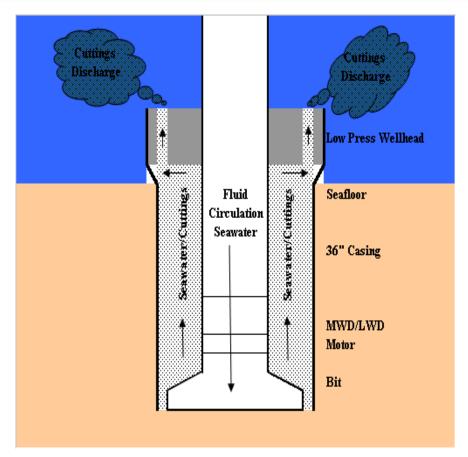
	26" Hole	17-1/2" Hole	12-1/4" Hole	8-1/2" Hole
Samples	-N.A	10m	10m 3m during show	10m 3m during show
Mud Log	-N.A	Drilling Parameter Mud Gas Lithology	Drilling Parameter Mud Gas Lithology	Drilling Parameter Mud Gas Lithology
Geochemistry	-N.A	Post-Drill	Post-Drill	Post-Drill
Biostratigraphy	-N.A	Post-Drill	Post-Drill	While Drilling
LWD	Gamma Ray Resistivity Sonic	Gamma Ray Resistivity Sonic	Gamma Ray Resistivity Sonic	Gamma Ray Resistivity Sonic
Open Hole Logs	-N.A	-N.A	Gamma Ray Induction Resistivity Density Neutron Sonic Micro-Imager Magnetic Borehole Siesmic Formation Pressure Fluid Sample	Gamma Ray Induction Resistivity Density Neutron Sonic Micro-Imager Magnetic Borehole Siesmic Formation Pressure Fluid Sample

Mobilization

- Rig scheduled to be mobilized from it's last work location (West Africa) to Columbia → ± 1 month
- Upon arriving in country it will go through immigration & customs clearance and undergo any required inspections at location
- The rig will be resupplied with required goods
- Upon arriving on location, the rig will set out DP beacons or deploy anchors depending on water depth & rig type
- ROV will performs a site survey of the well area prior to beginning operations



Execution: (1) **Jet-in the Structural Casing**



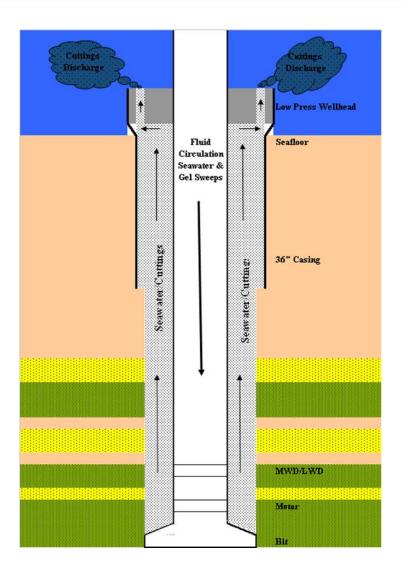
Purpose

- Primary Support for H/P wellhead & subsequent casing strings
- Relies on Sediment to Pipe Friction

Procedure

- Make up 36" casing string & L/P WH
- Run 26' bit & drill pipe inside 36", with WH running tool
- Engage L/P WH w/ running tools
- Run 36" casing to seafloor on drill pipe
- Begin pumping seawater down drill pipe to wash out sediments
- Lower 36" to desired penetration
- Shut down pumps and allow sediments to relax and hold 36" via skin friction

Execution: (2) Drill 26" Hole to Conductor Casing Depth



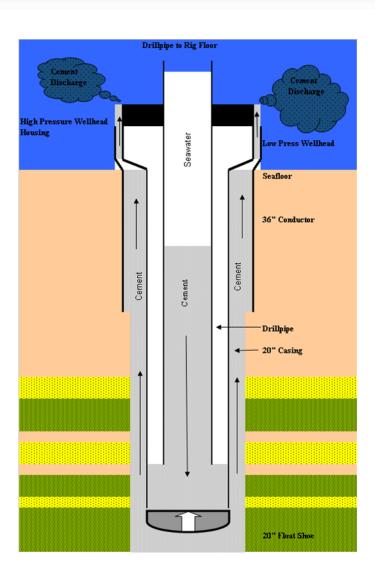
Purpose

- Provide Adequate Formation Strength
 - Achieve Returns to Surface
 - Support Mud Column
 - Provide for Ability to control well
- Typically 500-1200m bML

Procedure

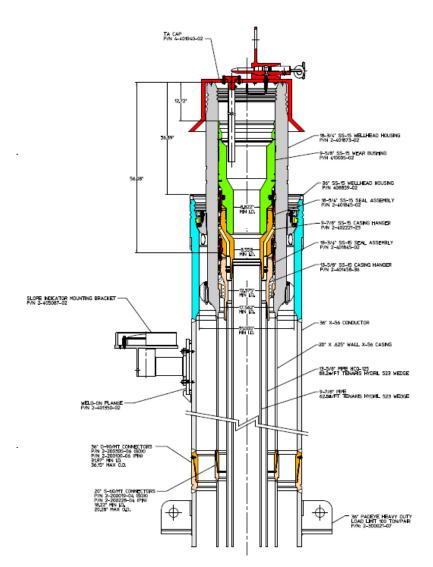
- After 36" is secured, release the wellhead running tools
- Resume pumping seawater and drill 26" hole
- Pump occasional sweeps of viscosified fluid (bentonite or guar gum) to clean cuttings from the hole
- Observe returns to the sea floor with the ROV's video system
- At desired depth, displace the hole with viscosified mud to stabilize while drill pipe is removed and casing is run in the hole

Execution: (3) Run & Cement 20" Conductor Casing



- Make up 20" casing
- Run inner cementing string
- Make up H/P WH on top of inner string, and attach to 20"
- Pick up and run 20" casing on drill pipe
- Stab the 20" into the L/P WH using ROV video to position rig as required
- Lower the 20" and land HPWH in LPWH
- Pump cement from casing shoe to mud line
- Release running tools and remove inner string

Execution – Subsea Wellhead



Low Pressure Housing

- Turquoise color
- Provides landing profile for HPWH
- Transfers loads into the 36" structural casing

High Pressure Housing

- Gray color
- 15,000 psi pressure rating
- Contains landing profiles for casing strings smaller than 20"
- Provides profile to connect BOP and marine riser to wellhead

Casing Hangers and packoffs

- Orange & lime green colors
- Supports casing string and seals annulus

Execution: Typical Subsea BOP

5 Ram Preventers

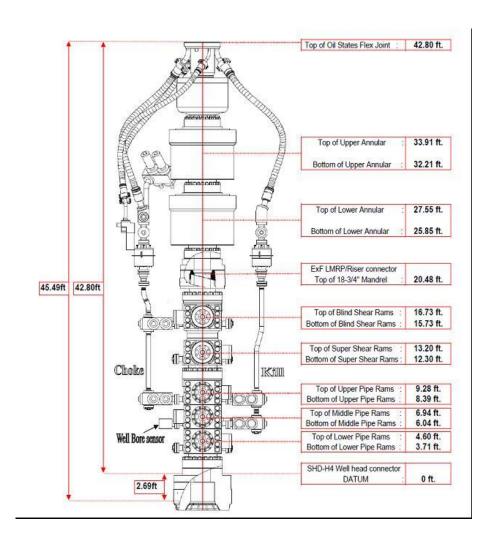
- 18-3/4", 15,000 psi WP
- Super shear rams capable of severing tube of all drill pipe and HWDP in use
- Blind shear rams capable of complete closure
- Lower ram cavity utilized as test ram

2 Annular Preventers

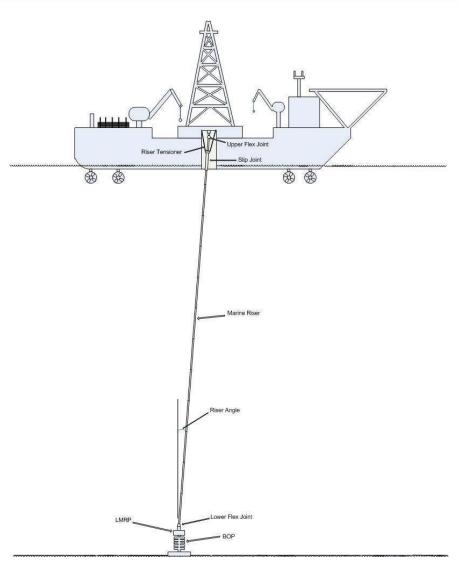
• 18-3/4", 10,000 psi WP

Functionality via

- 3 surface control panel
- Simrad acoustic system
- ROV



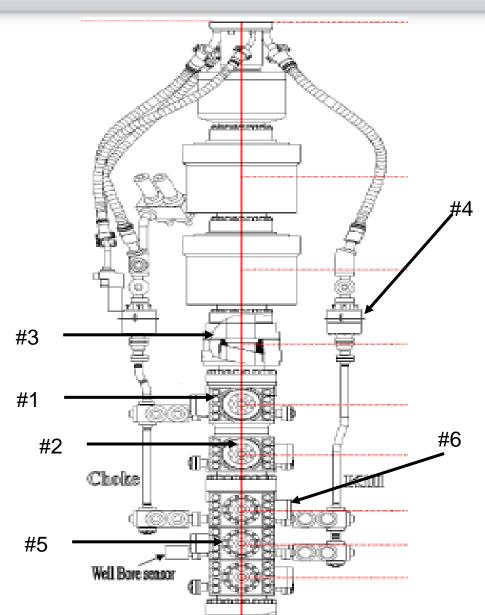
Execution: Run Marine Riser & Subsea BOP



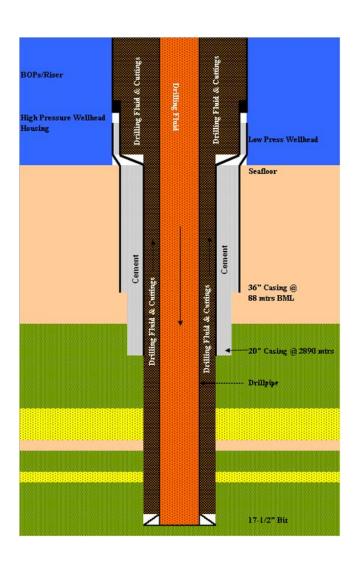
- Large diameter, hydraulic conduit
 - Allow fluids to transit from seafloor to vessel w/o contacting seawater
- Marine riser held motionless relative to seafloor
 - Vessel heave accommodated by telescoping "slip joint"
 - Vessel position & riser tension is managed to maintain low angles at top joint and BOP

Subsea BOP – Emergency Disconnect

- Manual initiation
- Automatic functionality
- 1) Blind Shear Rams close
- 2) Super Shear Rams close
- 3) Riser connector unlock
- 4) Collet connectors unlock
- 5) Middle Pipe Rams close
- 6) Upper Pipe Rams close



Execution: (4) Drill 17-1/2" Hole to Surface Casing Depth



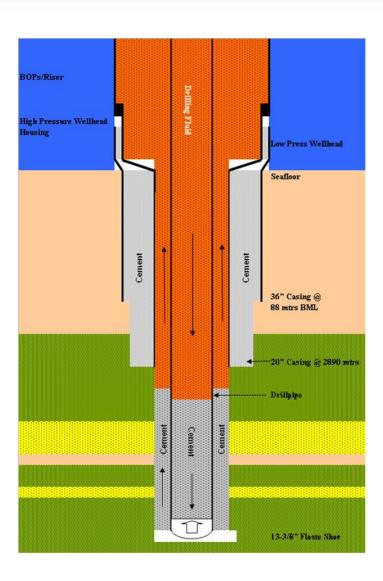
Purpose

- Provide Formation Integrity to reach Objectives
 - Support Mud Column
 - Provide for Ability to control well
 - Not Conducive to Logging (large hole)
- Typically set above first Well Objective

Procedure

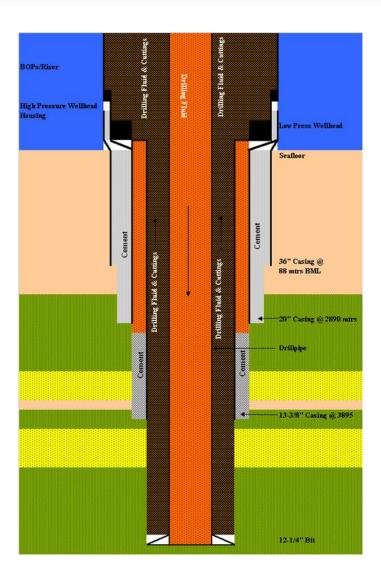
- Makeup and run the 17-½" drilling assembly
 - Bit
 - Logging While Drilling Tools / lWT
 - Drill collars & stabilizers
- Displace well to Low Toxicity Synthetic Base Mud (LTSBM)
 - Effectively Inhibits Hydrate Formation
 - Stabilizes reactive formations
 - Minimizes Hole Problems relative to Water Based Mud
- Drill 20" shoe track, perform Leak-off Test (LOT)
- Drill to casing point & condition mud
- Trip out of hole for casing

Execution: (5) Run & Cement 13-3/8" Surface Casing



- Make up 13⁵/₈" casing, casing hanger and packoff
- Run 13⁵/₈" casing on drill pipe
- Lower the 13%" and land the casing hanger in the HPWH
- Pump cement
- Release running tools
- Set & pressure test annular packoff
- Remove landing string

Execution: (6) Drill 12-1/4" Hole



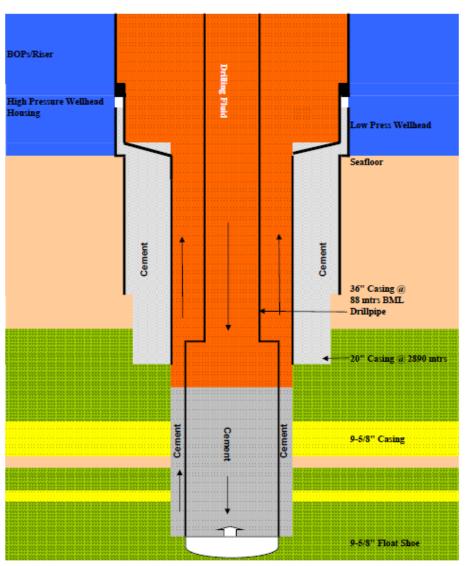
Purpose

- Provide Formation Integrity to reach Objectives
 - Support Mud Column
 - Provide for Ability to control well
 - Conducive to Logging
- Typically TD Hole Size
 - Full Wireline Evaluation Capability

Procedure

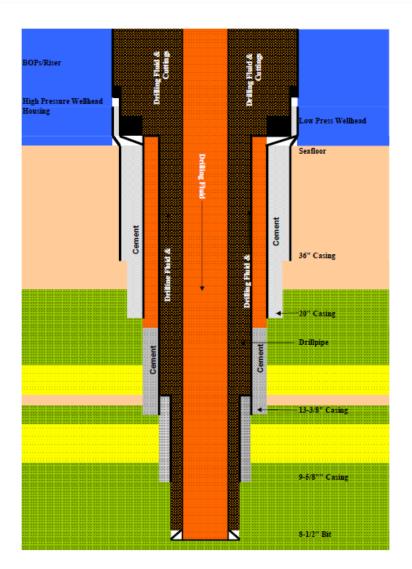
- Makeup and run the 12¼" drilling assembly
 - Bit
 - Logging While Drilling Tools
 - Drill collars & stabilizers
- Drill 13-3/8" float equipment
- Test BOP if required
- Perform LOT to ascertain good cement job and formation integrity
- Drill to next casing point
- Circulate and condition mud
- Trip out of hole for formation evaluation logs

Execution: (7) Run & Cement 9-5/8" Liner



- Setting Depth Based on Pore Pressure/Fracture Gradient
- Drilled with LTSBM
 - Full Wireline Evaluation Capability
- Full Well Control Capability
- Top of Cement to Liner Top

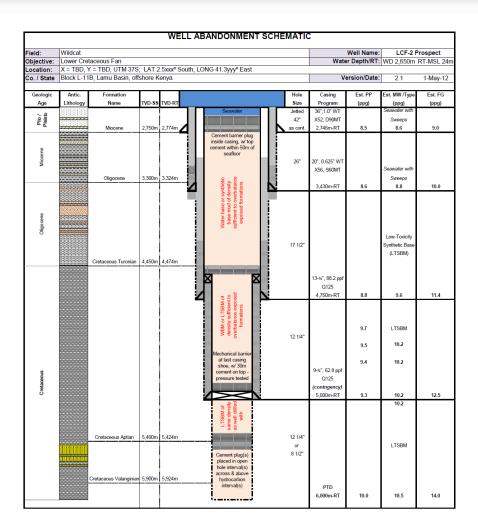
Execution: (7) 8-1/2" Production Hole (If Required)



- Total Depth based on Exploration Objectives
- Full Wireline Capability
- Full Well Control Capability
- 7" Liner Material Available if Justified
- Ideally used as a Contingency hole section in order to "Manage the Unknowns"

Execution: (8) Abandonment

- Isolate exposed formations in the well bore with tested mechanical barriers
 - Utilize cement plugs (gray) in open hole – placed opposite and above hydrocarbon intervals, leaving -
 - 'Void' intervals filled with drilling fluid of sufficient density to overbalance exposed formation after the riser is removed
 - Utilize a combination of cement and mechanical plugs inside casing



DeMobilization

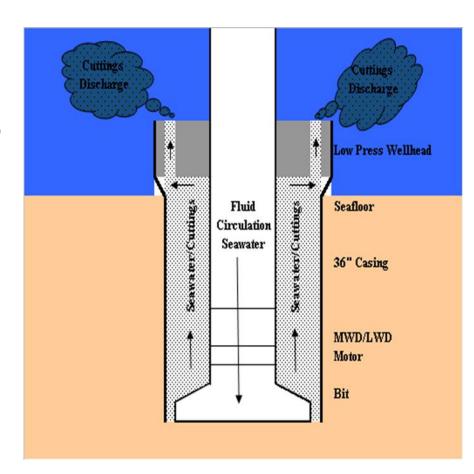
- ROV performs a site survey prior to departure from location to ensure the seafloor is clear
- Rig will recover DP beacons or anchors depending on rig type
- Rig will then travels to it's next location either in Columbia or exit the country



Treatment and Disposal of Drilling Fluid

Top Hole

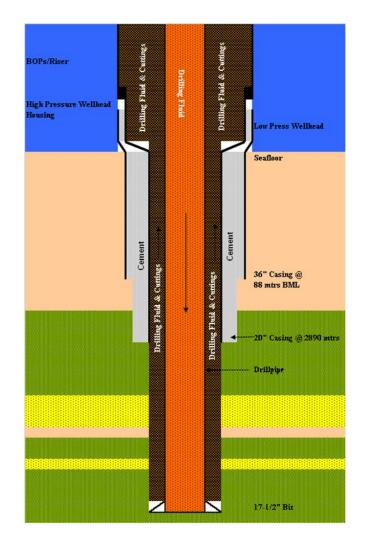
- Seawater is used to drill the top hole sections and is circulated back into the ocean
- There is no riser connected at this point, therefore the cuttings settle to the seafloor naturally
- The seawater is not treated but occasional non-toxic viscosified sweeps are pumped to flush the cuttings from the wellbore
- Before running the casing string, water based mud is pumped into the hole to provide hole stability until the casing is in place



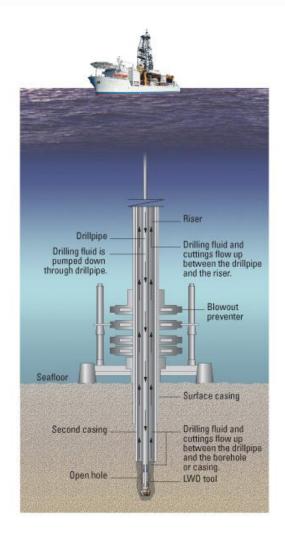
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Intermediate and Production Hole Sections

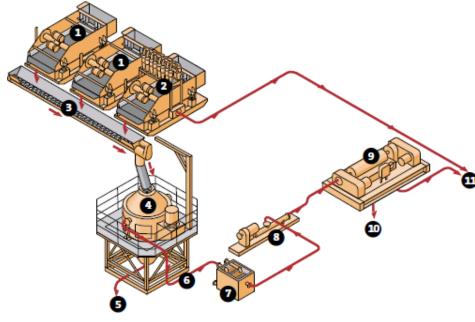
- LTSBM is used to drill these sections to prevent hydrates and to prevent hole stability issues from sensitive formations.
- The mud and cuttings are circulated back to the rig through the riser were the cuttings are separated through a series of equipment.
- After separation, the mud is cleaned and re-conditioned and the formation drill cuttings are disposed of in the ocean.
- At the end of the well, all LTSBM is either re-injected or sent back to shore to be recycled or disposed of at dedicated waste treatment facilities.



Drilling Fluid Circulating System



VERTI-G with Auger Feed



- Flow-line shaker
- 2 Mud cleaner
- Screw conveyor
- VERTI-G cuttings dryer
- Cuttings discharge
- 6 Recovered mud

- Catch tank
- Centrifuge feed pump
- Oentrifuge
- Solids discharge
- Clean mud to active